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The more specific immersion approach for observer design is then emphasized, while optimization-based methods are also presented as an alternative to analytic observers. Various practical application examples are included in those discussions, and some fields of application are further considered: first the problem of nonlinear output regulation is reformulated in a perspective of observers, and then the problem of parameter or fault estimation is briefly mentioned through some adaptive ...

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State observers for nonlinear systems. High gain, sliding mode and extended observers are the most common observers for nonlinear systems. To illustrate the application of sliding mode observers for nonlinear systems, first consider the no-input non-linear system:  $\dot{x} = (A - BK)x$

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*State observer - Wikipedia*

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The proposed schemes can be employed for different applications beyond those presented. The book presents solutions for the state estimation problem of unknown nonlinear systems based on two schemes. For the first one, a full state estimation problem is considered; the second one considers the reduced order case with, and without, the presence of unknown delays.

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